# ER3-600

# ER3-600,

### Maxium payload 3 kg with maxium reach 593 mm.

### Highlights

Thanks to its compact structure and built-in cable design, the ER3-600 can be easily integrated and installed, helping customers overcome harsh space installation requirements;

ER3-600 also has a customized disassembly version for education programs, which can meet the education requirements with intelligent manufacturing focus.

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### Applications

It can be used in handling operations, sorting, assembling, etc.

### Industries

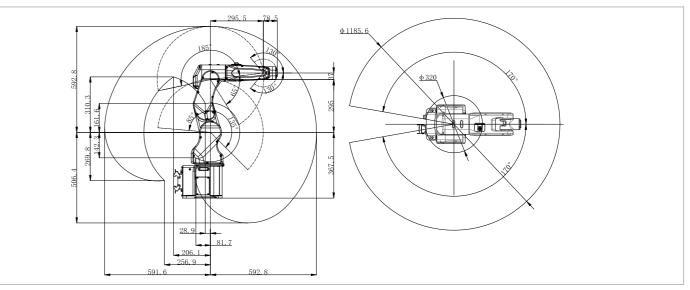
Suitable for electronic manufacturing, food and beverage, metal parts, education, plastic, pharmaceutical and other industries.

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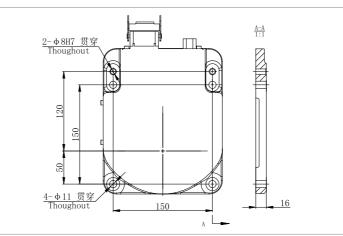
# SPECIFICATIONS

Model		ER3-600	Allowable load moment at wrist	J 4	4.45 N•m
Туре		Articulated		J 5	4.45 N•m
1996		Articulated		J 6	2.2 N•m
Controlled axes		6 Axes	Allowable load inertia at wrist	J 4	0.27 kg•m²
Max. payload on wrist		3 kg		J 5	0.27 kg·m²
Repeatability		±0.02 mm		J 6	0.03 kg•m²
<b>N I I I I</b>			Maximum speed	J1	400°/sec
Robot weight		27 kg		J 2	300°/sec
Reach		593 mm		J 3	520°/sec
Robot IP grade		IP40		J 4	500°/sec
Cabinet IP grade		IP20		J 5	530°/sec
cusineen grude		11 20		J 6	840°/sec
Drive mode		AC servo drive		J1	±170°
Installation		Floor, Upside-down, Wall, Angle		J 2	+85°/-135°
Installation enviroment	Ambient temperature	0~45 °C	Motion range	J 3	+185°/-65°
	Ambient			J 4	±190°
	humidity	RH≤80% (No dew nor frost allowed)		J 5	±130°
	Vibration acceleration	4.9 m/s <sup>2</sup> (<0.5 G)		J 6	±360°

# **OPERATING SPACE**



# BASE MOUNTING SIZE



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