

GR6100-2400

Maxium Reach:2374 mm /
Lemma Wrist / Max Payload:10 kg

■ Highlights

Provides floor mount, invert mount, wall mount and other installation methods;
The three-segment design of the upper arm and facilitate the disassembly, installation and integration;
configuration of the lemma 3R wrist has no singularity in front, which facilitates the integration;
The large diameter hollow wrist is configured, and the paint pipe can be arranged inside the wrist for easy integration;
It supports the expansion of additional axis;
Optional offline programming studio, standard painting process application, built-in peripheral equipment I/O, easy to program and integrate;
Through the explosion-proof certification of China, EU and ITTC, it can be used in zone 1 gas and zone 21 dust hazardous working environment.

■ Applications

Developed for general industrial painting applications is suitable for wood, furniture, ceramics, metal, hardware, containers, energy storage boxes, construction machinery, steel structure and other workpiece painting.

■ Industries

Suitable for wood, furniture, ceramics, metal, hardware, containers, energy storage boxes, construction machinery, steel structure and other industries.



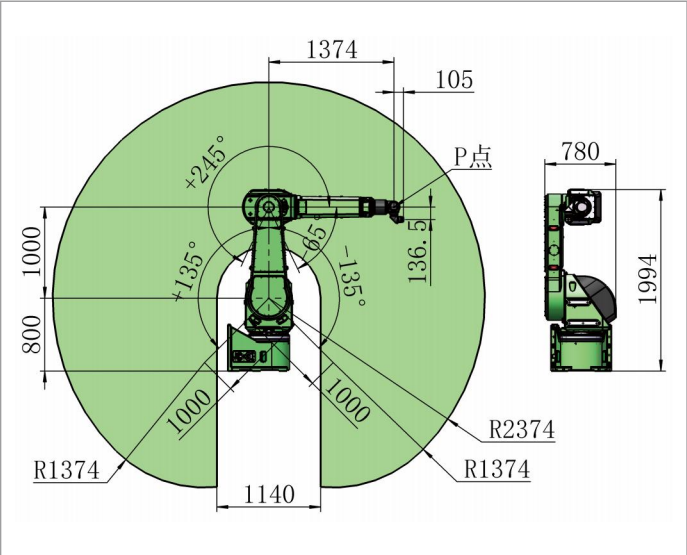
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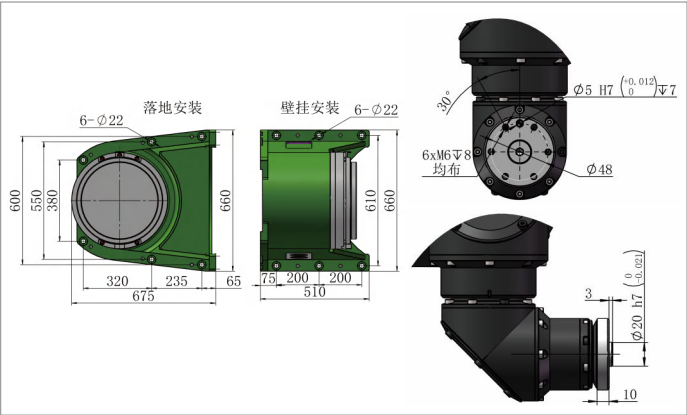
SPECIFICATIONS

Max. Payload on Wrist		10 kg	
Reach		2374 mm	
Repeatability		±0.15 mm	
Motion Range & Maximum Speed		Motion Range	Maximum Speed
	J1	±160°	100°/sec
	J2	±135°	100°/sec
	J3	-65°/+245°	120°/sec
	J4	±360°	360°/sec
	J5	±360°	400°/sec
Allowable Load Moment at Wrist	J4	30 N·m	
	J5	25 N·m	
	J6	12 N·m	
Allowable Load Inertia at Wrist	J4	0.8 kg·m ²	
	J5	0.59 kg·m ²	
	J6	0.1 kg·m ²	

OPERATING SPACE



BASE& END FLANGE MOUNTING SIZE

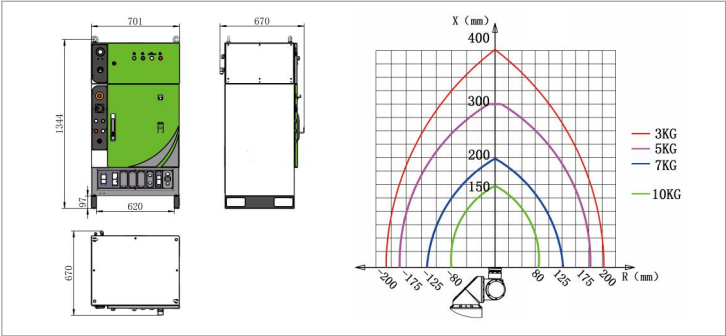


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GR-Series Painting Robot

Structure		6-Axis Series Structure	
Installation		Floor,Upside-down,Wall	
IP Grade	Robot	IP 65	
	Cabinet	IP 54	
Explosion-Proof	Gas	Ex db ib pxb IIC T4 Gb	
	Dust	Ex ib pxb tb IIIC T135°C Db	
Environment Requirements	Voltage	AC400V(±10%)	
	Power Capacity	11 kVA	
	Temperature	0-45 °C	
	Humidity	RH≤80%(No Condensation)	
Arm Payload	Outer Arm	15 kg	
	Inner Arm	15 kg	
Weight	Robot	645 kg	
	Cabinet	160 kg	

CONTROL CABINET SIZE&WRIST END LOAD MAP



SELECTION&CONFIGURATION TABLE

Item	Standard	Optional	
Driver	6 Axes	6+2 Axes	
Connector Cable	Static:8 m	Max:30 m	
	/	Towing Cable:Max 30 m	
Pendant	8 m	Max:30 m	
DI/DO	16/16	/	
AI/AO	/	Customized:Max 4	
Communication Mode	Ethercat	ProfiNet	CCLink
Memory Capacity	1GB	/	
Software Package	Painting Package	/	
Belt Tracking	/	Optional	
Color	RAL6018	Customized	

Information Release Time 2025/05